

COHEN-MACAULAYNESS OF SEMI-INVARIANTS FOR TORI

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ABSTRACT. In this paper we give a new method, in terms of one-parameter subgroups, to study semi-invariants for algebraic tori. In some cases we obtain extensions to results in [7]. In other cases we obtain different proofs.

1. INTRODUCTION

Let T be an algebraic torus over an algebraically closed field of characteristic zero and let W be a finite-dimensional representation of T . Then T acts on the polynomial ring $R = k[W]$ and by the Hochster-Roberts theorem [3], $k[W]^T$ is Cohen-Macaulay.

Let χ be some character of T . In [7, 8] Stanley defines R_χ^T to be the sum of all one-dimensional T -representations having character χ . It is clear that R_χ^T is an R^T -module. R_χ^T occurs naturally in the study of linear diophantine equations.

An interesting question is what is the depth of R_χ^T , in particular when R_χ^T is Cohen-Macaulay. Stanley gives an answer to this question in terms of certain polyhedral complexes whose dimension is of the order of $\dim W$ [7].

If G is an arbitrary algebraic group then in [9] we introduced a method to study R_χ^G (R_χ^G is defined similarly as R_χ^T). If $G = T$ is a torus then this approach is different from Stanley's method.

In the present paper we apply our techniques to the torus case. We obtain a description of the local cohomology modules $H_{(R^T)_+}^*(R_\chi^T)$ in terms of one-parameter subgroups of T (3.4.2). In this way one can compute the depth of R_χ^T . With our method we still need some spherical complexes, but these have dimension of the order of $\dim T$.

The methods used in this computation turn out to be a key ingredient in [10] where the same questions are studied for general reductive groups. There the situation is much more intractable, and it seems to be impossible to obtain an answer as complete as in the torus case.

Section 4 is devoted to some applications of our results. If $\dim T = 1$, we recover [7, Corollary 3.4]. We also completely analyze the case $\dim T = 2$ and we obtain a generalization [7, Corollary 3.4].

In §4.2 we show that R_χ^T is Cohen-Macaulay if the same holds for all one-parameter subgroups of T (4.2.1).

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In §4.3 we give a different proof of [7, Theorem 3.2].

In §4.4 we obtain (under some mild a priori hypothesis) necessary and sufficient conditions under which there exist only a finite number of χ for which R_χ^T is Cohen-Macaulay. It turns out that this is almost always the case.

In §4.5 we compute an explicit example and we obtain interesting counterexamples to the converses of [7, Theorem 3.2] and 4.2.1.

In §4.6 we give necessary and sufficient conditions for reciprocity [7] in terms of one-parameter subgroups of T . In particular we obtain that if $\dim T \leq 3$ and if reciprocity holds then R_χ^T is Cohen-Macaulay.

2. NOTATION AND CONVENTIONS

In this paper k always denotes an algebraically closed field of characteristic zero.

If T is a torus over k then $X(T)$ resp. $Y(T)$ will be the character group and the group of one-parameter subgroups of T . These are both free abelian groups and therefore the group laws will be written additively. We define $X(T)_\mathbb{R}$ as $\mathbb{R} \otimes_{\mathbb{Z}} X(T)$ and $Y(T)_\mathbb{R}$ as $\mathbb{R} \otimes_{\mathbb{Z}} Y(T)$. There is a natural pairing $Y(T) \times X(T) \rightarrow X(G_m) = \mathbb{Z}$ given by composition. This pairing will be denoted by $\langle \cdot, \cdot \rangle$. We will extend this pairing to $Y(T)_\mathbb{R} \times X(T)_\mathbb{R}$.

We will also choose a positive definite quadratic form on $Y(T)_\mathbb{R}$. The corresponding norm will be denoted by $\|\cdot\|$. Then we define

$$B(T) = \{\lambda \in Y(T) \mid \|\lambda\| < 1\} \quad \text{and} \quad S(T) = \{\lambda \in Y(T) \mid \|\lambda\| = 1\}.$$

Of course the results in this paper do not depend on the choice of $\|\cdot\|$.

Characters of T will be identified with one-dimensional representations of T . Hence the notation $\chi_1 \oplus \chi_2$ for $\chi_1, \chi_2 \in X(T)$ stands for the two-dimensional representation of T which is the direct sum of the one-dimensional representations determined by χ_1 and χ_2 . This is not to be confused with $\chi_1 + \chi_2$ which is just the sum of χ_1 and χ_2 in $X(T)$.

Let d be some positive integer and assume that V is a \mathbb{Z}^d -graded k -vector space. If x is a homogeneous element in V then $\deg x$ will be the degree of x . If $a = (a_1, \dots, a_d) \in \mathbb{Z}^d$ then V_a will be the homogeneous part of V of degree a .

The Poincaré series of V is defined as

$$(1) \quad P(V, t) = \sum_{a \in \mathbb{Z}^d} \dim(V_a) t^a,$$

where $t = (t_1, \dots, t_d)$ and $t^a = t_1^{a_1} \cdots t_d^{a_d}$. (1) is usually supposed to define an element of $t^{-\gamma} \mathbb{Z}[[t_1, \dots, t_d]]$ for some $\gamma \in \mathbb{Z}^d$. However in some occasions (1) will define an element of $t^\gamma \mathbb{Z}[[t_1^{-1}, \dots, t_d^{-1}]]$.

If E is a vector space and $x_1, \dots, x_d \in E$ is a set of points then by $\text{span}\{(x_i)_{i=1, \dots, d}\}$ we denote the subvector space of E spanned by $(x_i)_{i=1, \dots, d}$. By $\text{pos}\{(x_i)_{i=1, \dots, d}\}$ we mean the set of all positive linear combinations of $(x_i)_{i=1, \dots, d}$. This is a polyhedral cone (see [1]).

If A is a polyhedral cone or a spherical polyhedral set, then by the apex set, of A (notation: $\text{apex } A$) we denote the set $A \cap -A$. If A is a polyhedral cone then $\text{apex } A$ is a linear subspace of A .

In the sequel we will be mostly concerned with the following situation. An s -dimensional torus acts on a d -dimensional vector space W with basis $\{w_1, \dots,$

$w_d\}$ and corresponding weights $\alpha_1, \dots, \alpha_d$. To simplify the notation we will put $E = X(T)_{\mathbb{R}}$, $E^* = Y(T)_{\mathbb{R}}$, $S = S(T)$, $B = B(T)$.

Some other frequently used notations are $R = k[W]$, $X = \operatorname{Spec} k[W]$, $h = \dim R^T = \dim X/T$, $\mathscr{W} = \{1, \dots, d\}$ (the index set for the weights of W), X^u is the unstable locus in X , $X_\lambda = \{x \in X \mid \lim_{t \rightarrow 0} \lambda(t)x = 0\}$, $T_\lambda = \{i \in \mathscr{W} \mid \langle \lambda, \alpha_i \rangle < 0\}$, $d_\lambda = d - |T_\lambda|$, $\lambda \sim \lambda' \Leftrightarrow T_\lambda = T_{\lambda'}$, $\Lambda = B/\sim$, $B_\lambda = \{\mu \in B \mid \mu \sim \lambda\}$, $S_\lambda = \{\mu \in S \mid \mu \sim \lambda\}$, $\Phi_\lambda = \overline{B}_\lambda - B_\lambda$, $\Phi'_\lambda = \overline{S}_\lambda - S_\lambda$, M is the subsemigroup of $X(T)$ generated by $(\alpha_i)_{i=1, \dots, d}$, $E_\lambda = \operatorname{span}\{(\alpha_i)_{i \in T_\lambda}\}$, $A_\lambda = \operatorname{pos}\{(\alpha_i)_{i \in T_\lambda}\}$, $B_\lambda = \operatorname{pos}\{(\alpha_i)_{i \in T_\lambda}, (-\alpha_i)_{i \notin T_\lambda}\}$, $u_\lambda = \dim E_\lambda$.

3. LOCAL COHOMOLOGY OF SEMI-INVARIANTS

3.1 Generalities. Let G be a reductive algebraic group over k and let W be a finite-dimensional representation of G . Define $R = k[W]$, $d = \dim W$, $h = \dim R^G$ and let χ be an irreducible character of G .

In [8] Stanley defines R_χ^G as the sum of all irreducible representations of G in R , having character χ . Note that $R = \bigoplus_\chi R_\chi^G$ where χ runs over all irreducible characters of G . Furthermore it is easy to see that R_χ^G is finitely generated over R^G and hence $\dim R_\chi^G = \dim R^G$ if $R_\chi^G \neq 0$. One is often interested in the depth of R_χ^G or, more specifically, in the question of when R_χ^G is Cohen-Macaulay. See e.g. [9].

The following elementary lemma was used in [9]. Define $I = R(R^G)^+$.

Lemma 3.1.1. $H_{(R^G)^+}^*(R_\chi^G) = H_I^*(R)_\chi^G$ (with obvious notations).

Proof. Let f_1, \dots, f_u be a set of generators for $(R^G)^+$. Then the $(f_i)_i$ are obviously also R -generators for I . Let $K^*(R, f_1, \dots, f_u)$ be the complex

$$0 \rightarrow R \rightarrow \bigoplus_i R_{f_i} \rightarrow \bigoplus_{i,j; i < j} R_{f_i f_j} \rightarrow \dots \rightarrow R_{f_1 \dots f_u} \rightarrow 0$$

with the standard boundary maps. Then $H_I^*(R)_\chi^G = H^*(K^*(R, f_1, \dots, f_u))_\chi^G$. But, using the fact that G is reductive, we deduce

$$\begin{aligned} H^*(K^*(R, f_1, \dots, f_u))_\chi^G &= H^*(K^*(R, f_1, \dots, f_u)_\chi^G) \\ &= H^*(K^*(R_\chi^G, f_1, \dots, f_u)) \\ &= H_{(R^G)^+}^*(R_\chi^G), \end{aligned}$$

which is what we want. \square

Hence if $R_\chi^G \neq 0$ then R_χ^G is Cohen-Macaulay if and only if $H_I^i(R)_\chi^G = 0$ for $i = 0, \dots, h-1$.

Assume now that $G = T$ is an s -dimensional torus. In that case $R_\chi^T = \{r \in R \mid z.r = \chi(z)r \text{ for } z \in T\}$. Hence R_χ^T is an R^T -module of semi-invariants for the character χ .

We may choose a basis (w_1, \dots, w_d) in W such that the action of T on W is diagonal with respect to this basis; i.e., if $z \in T$ then $z.w_i = \alpha_i(z)w_i$ where the $(\alpha_i)_{i=1, \dots, d} \in X(T)$ are the weights of W .

We will sometimes assume that T acts faithfully on W . It is easy to see that this is equivalent with the following condition

$$(2) \quad \operatorname{span}\{(\alpha_i)_{i=1, \dots, d}\} = X(T)_{\mathbb{R}}.$$

We can make R into a \mathbb{Z}^d -graded ring by putting

$$\deg(w_i) = (0, \dots, 0, 1, 0, \dots, 0)$$

where the one occurs in the i th position. This grading is obviously compatible with the T -action and hence R^T and R_χ^T are also graded k -vector spaces.

It will be clear from Lemma 3.1.1 that our aim should be to describe $H_i^*(R)$. To this end we introduce some geometric notions.

Let $X = \operatorname{Spec} k[W]$. Then the radical of the ideal I is the defining ideal of the T -unstable locus in X , which will be denoted by X^u ; i.e.;

$$X^u = \{x \in X \mid 0 \in \overline{Tx}\}.$$

Using this notation we may write $H_i^*(R) = H_{X^u}(X, \mathcal{O}_X)$.

X^u may be described more conveniently using the Hilbert-Mumford criterion [6] which says that every point in X^u is unstable for some one-parameter subgroup of T ; i.e., if $\lambda \in Y(T)$ then one defines $X_\lambda = \{x \in X \mid \lim_{t \rightarrow 0} \lambda(t)x = 0\}$ and one obtains

$$(3) \quad X^u = \bigcup_{\lambda \in Y(T)} X_\lambda.$$

The closed points of X are in one-one correspondence with the elements of W^* . Let w_1^*, \dots, w_d^* be the dual basis of W^* . Then λ acts on W^* by $z \rightarrow \operatorname{diag}(z^{-\langle \lambda, \alpha_1 \rangle}, \dots, z^{-\langle \lambda, \alpha_d \rangle})$. Hence X_λ is the linear subspace of X spanned by the w_i^* where $\langle \lambda, \alpha_i \rangle < 0$.

Note that this description of X_λ makes sense if $\lambda \in Y(T)_{\mathbb{R}}$. Hence we will also use the notation X_λ for $\lambda \in Y(T)_{\mathbb{R}}$. However it is easy to see that there always exists a $\lambda' \in Y(T)$ such that $X_\lambda = X_{\lambda'}$.

To simplify the notation we will put $E = X(T)_{\mathbb{R}}$, $E^* = Y(T)_{\mathbb{R}}$, $S = S(T)$, and $B = B(T)$.

If $U \subset E^*$ then we define $X_U = \bigcup_{\lambda \in U} X_\lambda$. Using this notation, (3) may be rephrased as

$$X^u = X_{Y(T)} = X_{E^*} = X_{\overline{B}}.$$

Let $\mathscr{W} = \{1, \dots, d\}$. We define $T_\lambda = \{i \in \mathscr{W} \mid \langle \lambda, \alpha_i \rangle < 0\}$.

The following lemmas will be needed in the following sections.

Lemma 3.1.2. *Assume that $U_{1,2}$ are closed convex subsets of E^* such that $U_1 \cup U_2$ is convex. Then $X_{U_1 \cup U_2} = X_{U_1} \cap X_{U_2}$.*

Proof. It is clear that $X_{U_1 \cup U_2} \subset X_{U_1} \cap X_{U_2}$. To prove the opposite inclusion, take $\lambda_1 \in U_1$, $\lambda_2 \in U_2$. We have to find $\lambda \in U_1 \cup U_2$ such that $X_{\lambda_1} \cap X_{\lambda_2} \subset X_\lambda$ or equivalently $T_{\lambda_1} \cap T_{\lambda_2} \subset T_\lambda$. Using the hypothesis, we deduce that $[\lambda_1, \lambda_2] \cap U_1 \cap U_2 \neq \emptyset$. Hence we may take $\lambda \in [\lambda_1, \lambda_2] \cap U_1 \cap U_2$.

If $i \in T_{\lambda_1} \cap T_{\lambda_2}$ then $\langle \lambda_1, \alpha_i \rangle < 0$, $\langle \lambda_2, \alpha_i \rangle < 0$. But then it follows that also $\langle \lambda, \alpha_i \rangle < 0$. Hence $i \in T_\lambda$. \square

Lemma 3.1.3. *If $U \subset E^*$ then $X_U = X_{\overline{U}}$.*

Proof. If $\mathscr{W}' \subset \mathscr{W}$ then the condition $T_\lambda \supset \mathscr{W}'$ is an open condition on λ . From this the result follows. \square

3.2 A spectral sequence. We keep the same notation as before.

As we have seen, we have to be able to compute $H_{X_u}^*(X, \mathcal{O}_X)$. Furthermore $X^u = X_{\bar{B}}$. In this section we construct a spectral sequence which may be used to compute $H_{X_U}^*(X, \mathcal{O}_X)$ where U is a bounded closed convex subset of E^* .

Let $\chi_1, \dots, \chi_m \in E$ and let \mathcal{P} be the set of all nonempty subsets of U and ∂U of the form

$$\{\lambda \in U \mid \langle \lambda, \chi_i \rangle \geq 0 \text{ for } i \in \mathcal{W}_1, \langle \lambda, \chi_i \rangle = 0 \text{ for } i \in \mathcal{W}_2, \\ \langle \lambda, \chi_i \rangle \leq 0 \text{ for } i \in \mathcal{W}_3\}$$

and

$$\{\lambda \in \partial U \mid \langle \lambda, \chi_i \rangle \geq 0 \text{ for } i \in \mathcal{W}_1, \langle \lambda, \chi_i \rangle = 0 \text{ for } i \in \mathcal{W}_2, \\ \langle \lambda, \chi_i \rangle \leq 0 \text{ for } i \in \mathcal{W}_3\},$$

where $\mathcal{W} = \mathcal{W}_1 \cup \mathcal{W}_2 \cup \mathcal{W}_3$ is an arbitrary decomposition of \mathcal{W} as a disjoint union.

Furthermore $\mathcal{P}^1 = \{\sigma \in \mathcal{P} \mid \sigma \subset \partial U\}$ and $\mathcal{P}^0 = \mathcal{P} \setminus \mathcal{P}^1$.

If $\sigma, \sigma' \in \mathcal{P}$ then we will say that σ is a face of σ' if $\sigma \subset \sigma'$. σ is a facet of σ' if it is a face and $\dim \sigma = \dim \sigma' - 1$.

Let $\dim U = t$. We will assume that we have chosen $(\alpha_{\sigma, \sigma'})_{\sigma, \sigma' \in \mathcal{P}^0} \in \{-1, 1, 0\}$, $(\beta_{\sigma})_{\sigma \in \mathcal{P}^0, \dim \sigma = t} \in \{-1, +1\}$ with the following properties:

1. $\alpha_{\sigma', \sigma} = 0$ unless σ is a facet of σ' . In that case $\alpha_{\sigma', \sigma} = \pm 1$.
2. If $\sigma, \sigma'' \in \mathcal{P}^0$, $\dim \sigma'' = \dim \sigma + 2$, then

$$\sum_{\sigma' \in \mathcal{P}^0, \dim \sigma' = \dim \sigma + 1} \alpha_{\sigma'', \sigma'} \alpha_{\sigma', \sigma} = 0.$$

3. Let $\sigma \in \mathcal{P}^0$, $\dim \sigma = t - 1$, then

$$\beta_{\sigma'_1} \alpha_{\sigma'_1, \sigma} + \beta_{\sigma'_2} \alpha_{\sigma'_2, \sigma} = 0,$$

where σ'_1, σ'_2 are the two elements of \mathcal{P}^0 having σ as a facet.

As a final bit of notation we define for $U \subset V \subset E$ and for \mathcal{F} a sheaf on X , the maps $i_{U, V}(\mathcal{F})$ as the natural homomorphisms $H_{X_U}^*(X, \mathcal{F}) \rightarrow H_{X_V}^*(X, \mathcal{F})$ associated to the inclusions $X_U \subset X_V$.

Theorem 3.2.1. *With notation as above. Let \mathcal{F} be a quasicoherent sheaf on X . Then there is a spectral sequence*

$$(4) \quad E_{pq}^1 : \bigoplus_{\substack{\sigma \in \mathcal{P}^0 \\ \dim \sigma = p}} H_{X_\sigma}^q(X, \mathcal{F}) \Rightarrow H_{X_U}^{p+q-t}(X, \mathcal{F}),$$

where the boundary maps d_{pq} are given by $\bigoplus_{\sigma'} \sum_{\sigma} \alpha_{\sigma', \sigma} i_{\sigma, \sigma'}(\mathcal{F})$. Here the sum runs over all pairs (σ, σ') such that σ is a maximal face of σ' and has dimension p .

Theorem 3.2.1 will be applied as follows. Assume that the χ_1, \dots, χ_m are chosen in such a way that the elements of \mathcal{P} are the closed cells of a pseudo-manifold structure with boundary on U . We may then choose a set of incidence numbers $(\alpha_{\sigma', \sigma})_{\sigma', \sigma \in \mathcal{P}}$ as in [5, Theorem IV 7.2]. They obviously satisfy conditions 1 and 2.

Since U is orientable, we may choose a coherent orientation on U [5, IV paragraph 8]. From this one deduces there exist $(\beta_{\sigma})_{\sigma}$ satisfying condition 3.

To prove Theorem 3.2.1 we need the following lemma.

Lemma 3.2.2. *Assume that \mathcal{F} is a quasicohherent injective \mathcal{O}_X -module. Let $\mathcal{K}_{\mathcal{P}}(\mathcal{F})^*$ be the complex*

$$\xrightarrow{d_{p-1,0}} \bigoplus_{\sigma \in \mathcal{P}^0; \dim \sigma = p} \Gamma_{X_\sigma}(X, \mathcal{F}) \xrightarrow{d_{p,0}} \bigoplus_{\sigma \in \mathcal{P}^0; \dim \sigma = p+1} \Gamma_{X_\sigma}(X, \mathcal{F}) \xrightarrow{d_{p+1,0}}$$

and let

$$\varepsilon : \bigoplus_{\sigma \in \mathcal{P}^0; \dim \sigma = t} \Gamma_{X_\sigma}(X, \mathcal{F}) \rightarrow \Gamma_{X_U}(X, \mathcal{F})$$

be

$$(5) \quad \sum_{\dim \sigma = t} \beta_\sigma i_{\sigma, U}(\mathcal{F}).$$

Then

$$(6) \quad 0 \rightarrow \mathcal{K}_{\mathcal{P}}(\mathcal{F})^* \rightarrow \Gamma_{X_U}(X, \mathcal{F}) \rightarrow 0$$

is exact.

Proof. We will fix a particular \mathcal{F} and denote $\mathcal{K}_{\mathcal{P}}(\mathcal{F})^*$ by $\mathcal{K}_{\mathcal{P}}^*$.

It is clear that (6) is a complex. The proof that it is exact will be by induction on m . It will follow from the induction procedure described below that the starting cases are those where U is itself an element of \mathcal{P} . In those cases \mathcal{P}_0 consists of a single element U and hence the conclusion is obvious.

Define

$$U_+ = \{\lambda \in U \mid \langle \lambda, \chi_m \rangle \geq 0\}, \quad U_0 = \{\lambda \in U \mid \langle \lambda, \chi_m \rangle = 0\}, \\ U_- = \{\lambda \in U \mid \langle \lambda, \chi_m \rangle \leq 0\}.$$

Clearly $U_+ \cup U_- = U$, $U_+ \cap U_- = U_0$.

If $U_+ = U$ or $U_- = U$ then we can define \mathcal{P}^0 using only $\chi_1, \dots, \chi_{m-1}$. Hence the result follows by induction.

In the other case $\dim U_+ = \dim U_- = \dim U_0 + 1 = t$. We define $\mathcal{P}_\varepsilon = \{\sigma \in \mathcal{P} \mid \sigma \subset U_\varepsilon\}$ where $\varepsilon = \pm, 0$. $\mathcal{P}_+^0, \mathcal{P}_-^0, \mathcal{P}_0^0$ are defined as \mathcal{P}^0 , but using U_+, U_-, U_0 instead of U .

Given U_\pm, U_0 , we can define $\mathcal{P}_\pm^0, \mathcal{P}_0^0$ without using χ_m . Hence for U_\pm and U_0 the conclusion is true by induction on m .

The inclusions $\mathcal{P}_+^0, \mathcal{P}_-^0 \subset \mathcal{P}^0$ induce a map $\mathcal{K}_{\mathcal{P}_+}^* \oplus \mathcal{K}_{\mathcal{P}_-}^* \rightarrow \mathcal{K}_{\mathcal{P}}^*$. It is then easy to see that there is a short exact sequence of complexes

$$0 \rightarrow \mathcal{K}_{\mathcal{P}_+}^* \oplus \mathcal{K}_{\mathcal{P}_-}^* \rightarrow \mathcal{K}_{\mathcal{P}}^* \rightarrow \mathcal{K}_{\mathcal{P}_0}^* \rightarrow 0$$

which gives rise to a long exact homology sequence. We obtain at once that $H^q(\mathcal{K}_{\mathcal{P}}^*) = 0$ if $q \leq t - 2$.

Furthermore we may construct a commutative diagram:

$$(7) \quad \begin{array}{ccccccc} 0 & \longrightarrow & H^{t-1}(\mathcal{K}_{\mathcal{P}}^*) & \longrightarrow & H^{t-1}(\mathcal{K}_{\mathcal{P}_0}^*) & \longrightarrow & H^t(\mathcal{K}_{\mathcal{P}_+}^*) \oplus H^t(\mathcal{K}_{\mathcal{P}_-}^*) \\ & & & & \downarrow \bar{\varepsilon}_0 & & \downarrow (\bar{\varepsilon}_+, \bar{\varepsilon}_-) \\ & & 0 & \longrightarrow & \Gamma_{X_{U_0}}(X, \mathcal{F}) & \longrightarrow & \Gamma_{X_{U_+}}(X, \mathcal{F}) \oplus \Gamma_{X_{U_-}}(X, \mathcal{F}) \\ & & & & & & \longrightarrow H^t(\mathcal{K}_{\mathcal{P}}^*) \longrightarrow 0 \\ & & & & & & \downarrow \bar{\varepsilon} \\ & & & & & & \longrightarrow \Gamma_{X_U}(X, \mathcal{F}) \longrightarrow 0 \end{array}$$

Here the lower sequence is obtained from the Mayer Vietoris sequence, using the fact that $X_U = X_{U_+} \cup X_{U_-}$ and $X_{U_0} = X_{U_+} \cap X_{U_-}$ by Lemma 3.1.2. This sequence is exact since \mathcal{F} is injective.

ε_+ and ε_- are defined as ε , but using $(\beta_\sigma)_{\sigma \in \mathcal{P}_+^0; \dim \sigma = t}$, $(\beta_\sigma)_{\sigma \in \mathcal{P}_-^0; \dim \sigma = t}$ respectively.

The right most square in (7) is obviously commutative. Using this we may construct a map ε_0 which makes the left most square commutative. It is easy to compute that it has the form (5) (with different β 's) and hence $\bar{\varepsilon}_0$ is an isomorphism using the induction hypothesis. Since by the induction hypothesis, $\bar{\varepsilon}_+$, $\bar{\varepsilon}_-$ are also isomorphisms we deduce that $H^{t-1}(\mathcal{K}_\varphi^\bullet) = 0$ and that $\bar{\varepsilon}$ is an isomorphism. \square

Proof of Theorem 3.2.1. This is now standard. One starts with an injective resolution $0 \rightarrow \mathcal{F} \rightarrow \mathcal{F}^*$ and makes the double complex $\mathcal{K}_\varphi(\mathcal{F}^*)^*$. After taking homology for the first filtration on this double complex, we obtain the required spectral sequence. \square

3.3 Cohomology with support in a linear subspace. It will become clear in the next subsection that, to apply (4), we have to be able to compute $H_{X_\lambda}^*(X, \mathcal{O}_X)$. This is what we will do here.

To compute $H_{X_\lambda}^*(X, \mathcal{O}_X)$ we use the fact that the defining ideal of X_λ is generated by a subspace of W . Hence let W' be a subspace of W , spanned by some of the basis vectors $(w_i)_i$ and assume that $d' = \dim W'$. Put $W'' = W/W'$ and let J be the ideal generated by W' . We want to describe $H_J^i(R)$ as a \mathbb{Z}^d graded vector space (and hence as a T -module).

Proposition 3.3.1.

- $H_J^i(R) = 0$ if $i \neq d'$.
- $H_J^{d'}(R)$ is, as a \mathbb{Z}^d graded vector space, isomorphic to $(\bigwedge^{d'} W')^* \otimes \bigoplus_{n=0}^\infty S^n(W'^* \oplus W'')$.

Proof. The first statement is clear since J is generated by a regular sequence.

For the second statement, we use the fact that

$$H_J^{d'}(R) = \varinjlim_t \text{Ext}_R^{d'}(R/J^t, R).$$

We first compute

$$\text{Ext}^i(J^t/J^{t+1}, R) \cong (S^t W')^* \otimes \text{Ext}_R^i(R/J, R).$$

Again $\text{Ext}^i(R/J, R) = 0$ if $i \neq d'$. On the other hand, using the Koszul resolution, one easily computes that $\text{Ext}_R^{d'}(R/J, R) \cong (\bigwedge^{d'} W')^* \otimes R/J$. Hence as \mathbb{Z}^d -graded vector space

$$\begin{aligned} H_J^i(R) &= \bigoplus_t \bigoplus_{t'} \left(\bigwedge^{d'} W' \right)^* \otimes (S^t W')^* \otimes S^t W'' \\ &= \left(\bigwedge^{d'} W' \right)^* \otimes \bigoplus_{t \geq 0} S^t(W'^* \oplus W''). \quad \square \end{aligned}$$

In the sequel if $a = (a_1, \dots, a_d) \in \mathbb{Z}^d$ then $\text{supp}_- a$ will be $\{i | a_i < 0\}$. Let $\lambda \in E^*$ and define $d_\lambda = d - |T_\lambda|$.

Corollary 3.3.2.

- If $f \in H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X)$ then $\text{supp}_- \deg f = T_\lambda^c$ where c denotes the complement with respect to \mathcal{W} .
- $H_{X_\lambda}^i(X, \mathcal{O}_X) = 0$ if $i \neq d_\lambda$ and the weights of $H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X)$ are of the form

$$- \sum_{i \in T_\lambda^c} \alpha_i - \sum_{i \in T_\lambda^c} a_i \alpha_i + \sum_{i \in T_\lambda} b_i \alpha_i,$$

where $a_i, b_i \in \mathbb{N}$.

3.4 Interpretation of the spectral sequence. In this section we retain the notations of the previous sections. We will show how the spectral sequence (4) leads to a description of $H_{X_U}^*(X, \mathcal{O}_X)$ in terms of one-parameter subgroups in U .

If $\lambda, \mu \in E^*$ then we say that λ and μ are equivalent (notation $\lambda \sim \mu$) if $X_\lambda = X_\mu$ (or equivalently if $T_\lambda = T_\mu$). If $V \subset E^*$ then $V_\lambda = \{\mu \in V \mid \mu \sim \lambda\}$. We assume from now on that $U = \overline{B}$. This restriction is convenient but immaterial for the arguments presented below. B/\sim will be denoted by Λ .

We may define \mathcal{P} as in §3.2. We will assume that the χ_1, \dots, χ_m are chosen in such a way that the elements of \mathcal{P} define a structure of a pseudo-manifold with boundary on \overline{B} . This means we may choose $\alpha_{\sigma', \sigma}$ and β_σ , as explained in §3.2 after the statement of Theorem 3.2.1.

We will also assume that

$$(8) \quad \{\alpha_1, \dots, \alpha_d\} \subset \{\chi_1, \dots, \chi_m\}.$$

Then for every $\sigma \in \mathcal{P}^0$, $\text{relint } \sigma \subset B_\lambda$ for some $\lambda \in \sigma$. Hence $H_{X_\sigma}^*(X, \mathcal{O}_X) = H_{X_{\text{relint } \sigma}}^*(X, \mathcal{O}_X) = H_{X_\lambda}^*(X, \mathcal{O}_X)$ using Lemma 3.1.3.

Since $i_{\sigma\sigma'}(\mathcal{O}_X)$ is a graded map, it follows from Corollary 3.3.2 that if $\text{relint } \sigma \subset B_\lambda$, $\text{relint } \sigma' \subset B_\mu$ where $\lambda \not\sim \mu$ then $i_{\sigma'\sigma}(\mathcal{O}_X) = 0$. Hence $E_{pq}^1 = \bigoplus_{\lambda \in \Lambda} E_{\lambda, pq}^1$ where

$$(9) \quad E_{\lambda, pq}^1 = \bigoplus_{\text{relint } \sigma \subset B_\lambda; \dim \sigma = p} H_{X_\lambda}^q(X, \mathcal{O}_X)$$

and each E_λ^1 is closed under d . Hence we may write $d_{pq} = \bigoplus_\lambda d_{\lambda, pq}$ where $d_{\lambda, pq}$ goes from $E_{\lambda, pq}^1$ to $E_{\lambda, p+1q}^1$.

Let $\Phi_\lambda = \overline{B}_\lambda - B_\lambda$. This is a CW-subcomplex of \overline{B} . From the description (9) it is easy to see that the complex $(E_{\lambda, pq}^1, d_{\lambda, pq})$ has homology $H^p(\overline{B}_\lambda, \Phi_\lambda, k) \otimes H_{X_\lambda}^q(X, \mathcal{O}_X)$. It also follows from Corollary 3.3.2 that if $i \neq j$ or $\lambda \neq \mu$ then any graded map between $H_{X_\lambda}^i(X, \mathcal{O}_X)$ and $H_{X_\mu}^j(X, \mathcal{O}_X)$ must be 0.

Hence one deduces that (4) degenerates at the E^2 term. Using this one obtains that there is a T -equivariant filtration on $H_{X_U}^i(X, \mathcal{O}_X)$ (as an R -module) such that

$$\text{gr } H_{X_U}^i(X, \mathcal{O}_X) = \bigoplus_{p+q=i+s; \lambda \in \Lambda} H^p(\overline{B}_\lambda, \Phi_\lambda, k) \otimes_k H_{X_\lambda}^q(X, \mathcal{O}_X)$$

which may be simplified to give the following theorem.

Theorem 3.4.1. *With notations as above*

$$(10) \quad \operatorname{gr} H_{X^u}^i(X, \mathcal{O}_X) = \bigoplus_{\lambda \in \Lambda} \tilde{H}^{i+s-d_\lambda-1}(\Phi_\lambda, k) \otimes H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X).$$

Here we have used the standard convention $\tilde{H}^i(\emptyset, k) = k$ if $i = -1$ and $\tilde{H}^i(\emptyset, k) = 0$ if $i \neq -1$.

Corollary 3.4.2. *Assume that $a = (a_1, \dots, a_d) \in \mathbb{Z}^d$. Then for $H_{(RT)^+}^i(R_\chi^T)_a$ to be nonzero the following conditions must hold:*

- $\chi = a_1\alpha_1 + \dots + a_d\alpha_d$;
- $\exists \lambda \in Y(T) : \operatorname{supp}_- a = T_\lambda^c$ (such a λ is unique up to equivalence);
- $0 \leq d_\lambda - i \leq s$.

In that case $H_{(RT)^+}^i(R_\chi^T)_a$ will be isomorphic to $\tilde{H}^{i+s-d_\lambda-1}(\Phi_\lambda, k)$.

Recall that in [7] Stanley introduces for $a \in \mathbb{Z}^d$ polyhedral complexes Γ_a (which only depend on $\operatorname{supp}_- a$). The dimension of these complexes is in general of the order of d while the dimension of the Φ_λ 's is of the order of s .

The main result is that if $\chi = a_1\alpha_1 + \dots + a_d\alpha_d$, then

$$H_{(RT)^+}^i(R_\chi^T)_a \cong \tilde{H}_{h-i-1}(\Gamma_a, k).$$

We may then use Corollary 3.4.2 to compute $\tilde{H}_{h-i-1}(\Gamma_a, k)$ in some cases.

Corollary 3.4.3. *With notations as above. If there exists a λ such that $\operatorname{supp}_- a = T_\lambda^c$, then $\tilde{H}_{h-i-1}(\Gamma_a, k) \cong \tilde{H}^{i+s-d_\lambda-1}(\Phi_\lambda, k)$. Otherwise Γ_a is acyclic.*

The following proposition gives some trivial observations about the Φ_λ 's. The point is that, if $\lambda \approx 0$, we may replace Φ_λ with a subcomplex of the boundary complex of a spherical polytope.

Proposition 3.4.4.

- (1) Φ_0 is the empty set or a spherical polyhedral set (possibly the whole sphere).
- (2) If $\lambda \approx 0$ define $\Phi'_\lambda = \overline{S_\lambda} - S_\lambda$. Then $\tilde{H}^i(\Phi_\lambda, k) = \tilde{H}^{i-1}(\Phi'_\lambda, k)$.

Proof. (1) is easy. To prove (2) define the following sets

$$\Phi^{(1)} = \{\mu \in \Phi_\lambda \mid \|\mu\| \geq 1/4\}, \quad \Phi^{(2)} = \{\mu \in \Phi_\lambda \mid \|\mu\| \leq 3/4\}.$$

Then $\Phi^{(2)}$ is contractible. $\Phi^{(1)}$ is homotopy equivalent with a spherical polytope. Hence $\Phi^{(1)}$ is also contractible. Furthermore $\Phi^{(1)} \cap \Phi^{(2)}$ is homotopy equivalent with Φ'_λ . Since $\Phi_\lambda = \Phi^{(1)} \cup \Phi^{(2)}$, the result now follows from Mayer Vietoris. \square

Let C_0 be the apex set of $\operatorname{pos}\{(\alpha_i)_{i=1, \dots, d}\}$ and let $c = \dim C_0$. Then the set

$$\{\lambda \in B \mid \langle \lambda, \alpha_i \rangle = 0 \text{ if } \alpha_i \in C_0 \text{ and } \langle \lambda, \alpha_i \rangle < 0 \text{ otherwise}\}$$

represents a single equivalence class which we will denote by $\bar{\lambda}_n$. The following, somewhat technical result, will be used later.

Proposition 3.4.5.

- (1) Φ_{λ_n} is homeomorphic to a $s - c - 1$ -dimensional sphere.
- (2) If $i \neq h$ then $\tilde{H}^{i+s-d_{\lambda_n}-1}(\Phi_{\lambda_n}, k) = 0$; i.e., the term involving Φ_{λ_n} on the right-hand side of (10) does not contribute to $H_{X^u}^i(X, \mathcal{O}_X)$ for $i \neq h$.

Proof. (1) is clear by inspection. (2) depends on the following formula, which is also easy to verify:

$$h = |\{i | \alpha_i \in C_0\}| - c = d_{\lambda_n} - c.$$

Hence if $\tilde{H}^{i+s-d_{\lambda_n}-1}(\Phi_{\lambda_n}, k) \neq 0$ then $i + s - d_{\lambda_n} - 1 = s - c - 1$ which is equivalent with $i = d_{\lambda_n} - c = h$. \square

3.5 A new interpretation of Φ'_λ . Our aim is to give a new interpretation of the Φ'_λ (as defined in Proposition 3.4.4). This will make it easier to visualize what the structure of Φ'_λ is.

For $\lambda \in E^*$ define

$$\begin{aligned} A_\lambda &= \text{pos}\{(\alpha_i)_{i \in T_\lambda}\}, & E_\lambda &= \text{span}\{(\alpha_i)_{i \in T_\lambda}\}, \\ B_\lambda &= \text{pos}\{(\alpha_i)_{i \in T_\lambda}, (-\alpha_i)_{i \notin T_\lambda}\}. \end{aligned}$$

We start with a few lemmas that will be needed later.

Lemma 3.5.1. Assume that T acts faithfully on W . Then $\text{relint } B_\lambda = \text{int } B_\lambda$.

Proof. This follows from the definition of relint and the fact that B_λ spans E (using (2)). \square

Lemma 3.5.2. Assume that T acts faithfully on W . Then

$$\{(\alpha_i)_{i \in T_\lambda}\} \subset \partial \text{pos}\{(\alpha_i)_{i=1, \dots, d}\} \Leftrightarrow E_\lambda \cap \text{int } B_\lambda = \emptyset.$$

Proof. (\Leftarrow) Suppose that $E_\lambda \cap \text{int } B_\lambda = \emptyset$. This means by Lemma 3.5.1 that E_λ only hits ∂B_λ . We may then extend E_λ to a supporting hyperplane H for B . Then $(\alpha_i)_{i \in T_\lambda}, (-\alpha_i)_{i \notin T_\lambda}$ all lie on one side of H , but since the $(\alpha_i)_{i \in T_\lambda}$ lie in H we conclude that $(\alpha_i)_{i=1, \dots, d}$ all lie on the same side of H . Hence $\{(\alpha_i)_{i \in T_\lambda}\} \subset \partial \text{pos}\{(\alpha_i)_{i=1, \dots, d}\}$.

(\Rightarrow) To prove this direction we reverse the above argument. \square

Lemma 3.5.3. $A_\lambda \cap \text{apex } B_\lambda = 0$.

Proof. The apex of B_λ must lie in the hyperplane defined by λ . This hyperplane intersects A_λ only in 0. This proves what we want. \square

The following theorem will be our main result.

Theorem 3.5.4. Assume that T acts faithfully on W . Then Φ'_λ has the same homotopy type as $A_\lambda \cap \partial B_\lambda \cap S$.

Proof. Let $A_1 = A_\lambda \cap S$, $B_1 = B_\lambda \cap S$. Recall that if U_1 is a spherical polyhedral set then U_1^* is defined as $\{\mu \in S | \forall u \in U_1 : \langle \mu, u \rangle \leq 0\}$.

The lattice of faces of U_1 is the opposite of the lattice of faces of U_1^* . For a face \mathcal{F} of U_1 the corresponding face \mathcal{F}° of U_1^* is given by

$$(11) \quad \mathcal{F}^\circ = \{\lambda \in U_1^* | \forall u \in \mathcal{F} : \langle \lambda, u \rangle = 0\}.$$

Similarly $\mathcal{F} = \{u \in U_1 \mid \forall \lambda \in \mathcal{F}^\circ : \langle \lambda, u \rangle = 0\}$. From this definition it follows that

$$(12) \quad (\text{apex } U_1)^\circ = U_1^*.$$

We may now define S_λ as $\{\mu \in B_1^* \mid \forall a \in A_1 : \langle \mu, a \rangle < 0\}$.

Claim 1. $\text{relint } B_1^* \subset S_\lambda \subset B_1^*$. We have to prove that $B_1^* \setminus S_\lambda \subset \partial B_1^*$. Let $\mu \in B_1^* \setminus S_\lambda$. Then there is some $a \in A_1$ such that $\langle \mu, a \rangle = 0$.

By Lemma 3.5.3 a is not an apex of B_1 . Hence the hyperplane defined by μ intersects B_1 in a point which is not an apex. Therefore $\mu \in \partial B_1^*$ (using (12)).

Consequently $\Phi'_\lambda = \overline{S_\lambda} - S_\lambda = B_1^* - S_\lambda \subset \partial B_1^*$, and hence

$$(13) \quad \Phi'_\lambda = \{\mu \in \partial B_1^* \mid \exists a \in A_1 : \langle \mu, a \rangle = 0\}.$$

Define the following subcomplex of ∂B_1^* :

$$\Delta = \{\mathcal{F}^\circ \mid \mathcal{F} \text{ face of } \partial B_1, \mathcal{F} \cap A_1 \neq \emptyset\}.$$

Claim 2. $|\Delta| = \bigcup_{\mathcal{F}^\circ \in \Delta} \mathcal{F}^\circ = \Phi'_\lambda$. Let $\mu \in \mathcal{F}^\circ$ and choose $a \in \mathcal{F} \cap A_1$. Then a is an element of A_1 such that $\langle \mu, a \rangle = 0$ (11). Therefore by (13) $\mu \in \Phi'_\lambda$.

Conversely let $\mu \in \Phi'_\lambda$. Then by (13) there exists an $a \in A_1$ such that $\langle \mu, a \rangle = 0$. By 3.5.1 μ cannot be everywhere 0 on B_1 and hence $a \in \partial B_1$. Let \mathcal{F} be the smallest face of ∂B_1 containing a . then $\mathcal{F}^\circ \in \Delta$ and μ must also vanish on \mathcal{F} . Therefore $\mu \in \mathcal{F}^\circ$ (11). Now let $\mu' \in \mathcal{F}^\circ$ be arbitrary. Then μ' vanishes on \mathcal{F} and in particular on a . Therefore $\mu' \in \Phi'_\lambda$ and we have shown that $\mu \in \mathcal{F}^\circ \subset \Phi'_\lambda$. This proves our claim.

Let $L(\Delta)$ resp. $L(A_1 \cap \partial B_1)$ be the lattices of faces of Δ and $A_1 \cap \partial B_1$. Then there exists a map $\phi: L(\Delta) \rightarrow L(A \cap \partial B)^{\text{opp}}: \mathcal{F}^\circ \mapsto \mathcal{F} \cap A_1$.

Furthermore if $\mathcal{G} \in L(A \cap \partial B)^{\text{opp}}$ then (as in [4, p. 93])

$$\phi/\mathcal{G} = \{F^\circ \mid \phi(F^\circ) \leq \mathcal{G}\} = \{\mathcal{F}^\circ \mid \mathcal{F} \cap A_1 \supset \mathcal{G}\}.$$

Define $\mathcal{G}' = \bigcap_{\mathcal{F} \cap A_1 \supset \mathcal{G}} \mathcal{F}$. Then $\mathcal{G}'^\circ \in L(\Delta)$ and $\phi/\mathcal{G} = \{\mathcal{F}^\circ \mid \mathcal{F} \supset \mathcal{G}'\} = \{\mathcal{F}^\circ \mid \mathcal{G}'^\circ \supset \mathcal{F}^\circ\}$ is contractible and hence by [4, Theorem A, p. 93] ϕ induces a homotopy equivalence between $|L(\Delta)|$ and $|L(A_1 \cap \partial B_1)^{\text{opp}}|$.

Since $\Phi'_\lambda = |L(\Delta)|$ and

$$|L(A_1 \cap \partial B_1)^{\text{opp}}| \cong |L(A_1 \cap \partial B_1)| \cong A_1 \cap \partial B_1,$$

we are done. \square

3.6 The structure of some special Φ'_λ . In general, the structure of Φ'_λ can be arbitrarily complicated in the sense that apart from the fact that Φ'_λ should be a subcomplex of the boundary complex of a spherical polytope, there are no other restrictions. However for some special λ 's the structure of Φ'_λ can be described.

On $\Lambda - \{\bar{0}\}$ we define a partial ordering as follows:

$$(14) \quad \bar{\lambda}_1 \leq \bar{\lambda}_2 \Leftrightarrow \text{relint pos}\{(\alpha_i)_{i \in T_{\lambda_1}}\} \subset \text{relint pos}\{(\alpha_i)_{i \in T_{\lambda_2}}\}.$$

Then it turns out that for the maximal elements under this ordering Φ'_λ is either contractible or homotopy equivalent with a sphere.

The following proposition shows that \leq does indeed define a partial ordering on $\Lambda - \{\bar{0}\}$.

Proposition 3.6.1. *If $\bar{\lambda}_{1,2} \in \Lambda - \{0\}$, $\bar{\lambda}_1 \leq \bar{\lambda}_2$ then $T_{\lambda_1} \subset T_{\lambda_2}$.*

Proof. By taking closures, it follows from (14) that $\bar{\lambda}_1 \leq \bar{\lambda}_2$ implies that $\forall i \in T_{\lambda_1} : \alpha_i \in \text{pos}\{(\alpha_j)_{j \in T_{\lambda_2}}\}$.

Fix $i \in T_{\lambda_1}$. Since $\alpha_i \neq 0$, α_i must be strictly positive linear combinations of some of the $(\alpha_j)_{j \in T_{\lambda_2}}$. Hence $\langle \lambda_2, \alpha_i \rangle < 0$ and therefore $i \in T_{\lambda_2}$. \square

Corollary 3.6.2. *If $\bar{\lambda}_1 \leq \bar{\lambda}_2$ and $\bar{\lambda}_2 \leq \bar{\lambda}_1$ then $\lambda_1 \sim \lambda_2$.*

We will prove the following fact.

Theorem 3.6.3. *Assume that T acts faithfully on W . Let λ be maximal with respect to the partial ordering defined on $\Lambda - \{0\}$. Then*

1. *If $\{(\alpha_i)_{i \in T_\lambda}\} \subset \partial \text{pos}\{(\alpha_i)_{i=1,\dots,d}\}$ then Φ'_λ is contractible and hence $\tilde{H}^i(\Phi'_\lambda, k) = 0$ for all i ;*

2. *Otherwise, Φ'_λ is homotopic to a $u_\lambda - 2$ dimensional sphere where $u_\lambda = \dim E_\lambda$. Hence*

$$\tilde{H}^i(\Phi'_\lambda, k) = \begin{cases} k & \text{if } i = u_\lambda - 2, \\ 0 & \text{otherwise.} \end{cases}$$

Recall that E_λ was defined in the beginning of §3.5.

The proof of Theorem 3.6.3 will be based upon a series of lemmas.

Lemma 3.6.4. *Assume that we have chosen $T \subset \{1, \dots, d\}$, $\mu \in E^* - \{0\}$ such that $T \subset T_\mu$. Assume furthermore that there exists*

$$y \in E_\mu \cap \text{pos}\{(\alpha_i)_{i \notin T}\}$$

with the property that $\langle \mu, y \rangle < 0$. Then there exist $\lambda \in E^ - \{0\}$, $T' \subset \{1, \dots, d\}$ with the property that*

1. *$T \subsetneq T' \subset T_\lambda$ and*

2. *$\text{relint pos}\{(\alpha_i)_{i \in T}\} \subset \text{relint pos}\{(\alpha_i)_{i \in T'}\}$.*

Proof. Choose $y \in E_\mu \cap \text{pos}\{(\alpha_i)_{i \notin T}\}$ such that y may be written as

$$(15) \quad y = \sum_{i \in T''} a_i \alpha_i, \quad \text{all } a_i > 0$$

with the smallest possible $T'' \subset T^c$ such that $\langle \mu, y \rangle < 0$. In particular $T'' \neq \emptyset$.

Choose $z \in \text{relint pos}\{(\alpha_i)_{i \in T}\}$, i.e.,

$$z = \sum_{i \in T} b_i \alpha_i, \quad \text{all } b_i > 0.$$

Since also $y \in E_\lambda$ we may also choose $(a_i)_{i \in T} \in \mathbb{R}$ such that

$$(16) \quad y = \sum_{i \in T} (-a_i) \alpha_i.$$

Define $T' = T \cup T''$. Subtracting (16) from (15) yields $0 = \sum_{i \in T'} a_i \alpha_i$. Then, for $t > 0$ small enough, the expression

$$z = \sum_{i \in T} (b_i + t a_i) \alpha_i + \sum_{i \in T''} t a_i \alpha_i$$

will have positive coefficients. This shows that $z \in \text{relint pos}\{(\alpha_i)_{i \in T'}\}$ which proves 2 and part of 1.

To verify the existence of λ we have to show that

$$(17) \quad 0 \notin \text{relint pos}\{(\alpha_i)_{i \in T'}\}.$$

Assume that there are $(u_i)_{i \in T'}$ such that

$$0 = \sum_{i \in T'} u_i \alpha_i, \quad \text{all } u_i > 0.$$

Then for $t > 0$,

$$y' = y - t \sum_{i \in T''} u_i \alpha_i$$

still lies in E_μ and has the property that $\langle \mu, y' \rangle < 0$.

Moreover, if we choose $t = \min_{i \in T''} a_i / u_i$ then $y' = \sum_{i \in T''} (a_i - tu_i) \alpha_i$ is in $\text{pos}\{(\alpha_i)_{i \notin T}\}$ and has smaller support than y . This contradicts the choice of y . \square

Lemma 3.6.5. *Let $T \subset \{1, \dots, d\}$, $\mu \in E^* - \{0\}$ be such that $T \subset T_\mu$. Then there exist $\lambda \in E^* - \{0\}$ such that*

$$\text{relint pos}\{(\alpha_i)_{i \in T}\} \subset \text{relint pos}\{(\alpha_i)_{i \in T_\lambda}\}.$$

Proof. Assume that the result is false and let (T, μ) be a counterexample with T maximal.

Let $E_{\mu 0} = E_\mu \cap \ker \mu$. By the previous lemma we may assume that for all $y \in E_\mu \cap \text{pos}\{(\alpha_i)_{i \notin T}\}$ it is true that $\langle \mu, y \rangle \geq 0$; i.e., $E_\mu \cap \text{pos}\{(\alpha_i)_{i \notin T}\}$ lies on one side of $E_{\mu 0}$ whereas the $(\alpha_i)_{i \in T}$ lie strictly on the other side.

It is then easy to see that we may extend $E_{\mu 0}$ to a hyperplane in E , separating $(\alpha_i)_{i \in T}$ from $(\alpha_i)_{i \notin T}$. Hence $T = T_\lambda$. This contradicts the fact that (T, μ) was a counterexample. \square

Lemma 3.6.6. *Let $\lambda \in \Lambda - \{0\}$ be maximal for the partial ordering defined by (14). Then $A_\lambda = B_\lambda \cap E_\lambda$.*

Proof. Certainly $A_\lambda \subset B_\lambda \cap E_\lambda$. To prove the converse let

$$\beta_i = \begin{cases} \alpha_i & \text{if } i \in T_\lambda, \\ -\alpha_i & \text{if } i \notin T_\lambda. \end{cases}$$

Let y be the element of $B_\lambda \cap E_\lambda \setminus A_\lambda$ which can be expressed in the form

$$y = \sum_{i \in T} a_i \beta_i, \quad \text{all } a_i > 0,$$

with smallest possible T . Note that $\beta_i \neq 0$ for $i \in T \cup T_\lambda$.

Claim. $\text{pos}\{(\beta_i)_{i \in T}\} \cap A_\lambda = \{0\}$. Suppose not. Then there exist $z = \sum_{i \in T} b_i \beta_i \in A_\lambda$ with $b_i \geq 0$ and not all $b_i = 0$.

Let $t = \min_{i \in T} a_i / b_i$. Then $y' = y - tz$ has smaller support than y . Furthermore, since $y = y' + tz$, we see that $y' \in B_\lambda \cap E_\lambda \setminus A_\lambda$, contradicting the minimality of T . This proves our claim. In particular $T \cap T_\lambda = \emptyset$.

Using the Claim, we may now choose a $\mu \in E^* - \{0\}$ strictly separating $(\beta_i)_{i \in T}$ and $(\beta_i)_{i \in T_\lambda}$; i.e.,

$$\forall i \in T_\lambda : \langle \mu, \beta_i \rangle < 0, \quad \forall i \in T : \langle \mu, \beta_i \rangle > 0.$$

Hence $T_\lambda \subset T_\mu$.

We deduce that

$$-y = \sum_{i \in T} a_i \alpha_i \in E_\lambda \cap \text{pos}\{(\alpha_i)_{i \in T_\lambda^c}\}$$

has the property that $\langle \mu, -y \rangle < 0$.

But then by Lemma 3.6.4 and Lemma 3.6.5 there exists $\lambda' \in E^* - \{0\}$ such that $T_\lambda \subsetneq T_{\lambda'}$ and

$$\text{relint pos}\{(\alpha_i)_{i \in T_\lambda}\} \subset \text{relint pos}\{(\alpha_i)_{i \in T_{\lambda'}}\}.$$

But since λ was chosen to be maximal under the partial ordering defined by (14), we obtain a contradiction. \square

Proof of Theorem 3.6.3. This is now a simple application of Theorem 3.5.4, Lemma 3.5.1 and Lemma 3.5.2.

In the first case Φ'_λ will have the homotopy type of $A_\lambda \cap S$ which is contractible.

In the second case Φ'_λ will have the homotopy type of $\partial A_\lambda \cap S$ which is a $u_\lambda - 2$ dimensional sphere. \square

4. APPLICATIONS

In this section we retain the notations of the previous sections.

We will give some applications of Theorem 3.4.1. However, before we continue, it is useful to introduce the concept of stability.

A point $x \in X$ is said to be stable if for all $\lambda \in Y(T) - \{0\}$ neither $\lim_{t \rightarrow 0} \lambda(t)x$ nor $\lim_{t \rightarrow \infty} \lambda(t)x$ exists. Stable points have finite stabilizer and closed T -orbit. They form an invariant open subset of X . One deduces that if X has a stable point then $d = \dim R = \dim R^T + \dim T = h + s$. It is easy to see that X has a stable point if and only if for all $\lambda \in Y(T) - \{0\}$ there exists an i such that $\langle \lambda, \alpha_i \rangle > 0$. This means that the weights of W do not lie in a halfspace defined by a hyperplane in E going through the origin.

It will become clear below that 3.4.1 is best suited for cases where X has a stable point. This is the most interesting situation from a geometric viewpoint. Of course other cases can also be treated but then things are not as natural.

4.1 $\dim T = 1$ or 2 . As a first application we note that it is easy to eyeball what the possible Φ_λ 's are if $\dim T$ is small.

Let us first consider the case $\dim T = 1$. To avoid triviality we assume that T acts faithfully on X . There are now two possibilities.


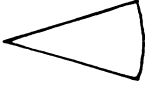
- *X does not have a stable point.* This is the trivial case. We obtain that $\Lambda = \{\bar{0}, \bar{\lambda}\}$ where Φ_0 consists of one point and Φ_λ consists of two points. Hence $H_{X^u}^i(X, \mathcal{O}_X) = H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X)^{\delta_{id_\lambda}}$ where δ is the Kronecker delta. One obtains, using [2, Satz 4.10 and 4.12], that if $R_\lambda^T \neq \{0\}$ then $\dim R_\lambda^T = d_\lambda$ and R_λ^T is Cohen-Macaulay. Of course this can be verified directly without any difficulty.

- *X does have a stable point.* In this case $\Lambda = \{\bar{0}, \bar{\lambda}_1, \bar{\lambda}_2\}$ where $\Phi_0 = \emptyset$ and $\Phi_{\lambda_1} \cong \Phi_{\lambda_2} \cong 2$ points. If we put this information in Corollary 3.4.2, we obtain a simple proof for [7, Theorem 3.3 and Corollary 3.4].

The conclusion of Theorem 3.4.1 may be written as

$$(18) \quad \text{gr } H_{X^u}^i(X, \mathcal{O}_X) = H_{X_{\lambda_1}}^{d_{\lambda_1}}(X, \mathcal{O}_X)^{\delta_{id_{\lambda_1}}} \oplus H_{X_{\lambda_2}}^{d_{\lambda_2}}(X, \mathcal{O}_X)^{\delta_{id_{\lambda_2}}} \oplus H_{\{0\}}^d(X, \mathcal{O}_X)^{\delta_{id-1}}.$$

TABLE 1

| Type | Φ_λ | $\dim \tilde{H}^i(\Phi_\lambda, k)$ | | |
|------|---|-------------------------------------|---------|---------|
| | | $i = -1$ | $i = 0$ | $i = 1$ |
| 1 | \emptyset | 1 | 0 | 0 |
| 2 | \bullet | 0 | 0 | 0 |
| 3 | $)$ | 0 | 0 | 0 |
| 4 | $\bullet \quad \bullet$ | 0 | 1 | 0 |
| 5 | $\bullet \quad)$ | 0 | 1 | 0 |
| 6 |  | 0 | 0 | 0 |
| 7 |  | 0 | 0 | 1 |

Let us now consider the case $\dim T = 2$. We will assume that T acts faithfully on W . In that case we can construct Table 1 (we have used an iconic representation of Φ_λ which we hope is sufficiently clear). Note that types 2 and 3 only occur if X has no stable point.

Corollary 3.4.2 together with Table 1 gives now a complete description of the groups $H_{(RT)^+}(R_\chi^T)$ if $\dim T = 2$. We will illustrate this in the case that X has a stable point. It follows from Table 1 that if $\lambda \neq 0$ then Φ'_λ is either the empty set, one point or two points. Hence we may define a partition by $\Lambda - \{0\} = \Lambda_\emptyset \cup \Lambda_\bullet \cup \Lambda_{\bullet\bullet}$. Then there is the following analog to [8, Corollary 3.4].

Corollary 4.1.1. *Assume that X has a stable point. Let $\mathcal{U}^\chi \subset \mathbb{Z}^d$ be the set of all integer solutions to $\sum_{i=1}^d a_i \alpha_i = \chi$, and define*

$$\Lambda_\emptyset^\chi = \{\bar{\lambda} \in \Lambda_\emptyset \mid \exists a \in \mathcal{U}^\chi : \text{supp}_- a = T_\lambda^c\}$$

and similarly

$$\Lambda_{\cdot}^{\chi} = \{\bar{\lambda} \in \Lambda_{\cdot} \mid \exists a \in \mathcal{U}^{\chi} : \text{supp}_{-} a = T_{\lambda}^c\}.$$

Assume that $R_{\chi}^T \neq 0$. Then

$$\text{depth } R_{\chi}^T = \min\{(d_{\lambda} - 1)_{\lambda \in \Lambda_{\emptyset}^{\chi}}, (d_{\lambda})_{\lambda \in \Lambda_{\cdot}^{\chi}}\}.$$

In particular R_{χ}^T is Cohen-Macaulay if and only if

$$|T_{\lambda}| \leq 1 \text{ for all } \bar{\lambda} \in \Lambda_{\emptyset}^{\chi} \text{ and } |T_{\lambda}| \leq 2 \text{ for all } \bar{\lambda} \in \Lambda_{\cdot}^{\chi}.$$

Proof. This is a direct consequence of Corollary 3.4.2. For the criterion for Cohen-Macaulayness we use the fact that $d_{\lambda} = d - |T_{\lambda}|$ and $h = d - 2$ (using the stability hypothesis). \square

Remark 4.1.2. This criterion is particularly simple to apply if for all $\bar{\lambda} \in \Lambda_{\emptyset} : |T_{\lambda}| > 1$ and for all $\bar{\lambda} \in \Lambda_{\cdot} : |T_{\lambda}| > 2$. In that case R_{χ}^T will be Cohen-Macaulay if and only if

$$\forall \bar{\lambda} \in \Lambda_{\emptyset} \cup \Lambda_{\cdot} : \nexists a \in \mathcal{U}^{\chi} : \text{supp}_{-} a = T_{\lambda}^c.$$

To finish this section, we will give a criterion to decide whether $\bar{\lambda} \in \Lambda - \{0\}$ belongs to Λ_{\emptyset} , to λ_{\cdot} or to Λ_{\cdot} . Note that $\Lambda - \{0\} = S / \sim$.

Let us call $\lambda \in S$ a local maximum if there exists an arc $[\lambda_1, \lambda_2] \subset S$ containing λ in its interior, such that for all $\mu \in [\lambda_1, \lambda_2]$, $d_{\mu} \leq d_{\lambda}$, and $d_{\lambda_1}, d_{\lambda_2} < d_{\lambda}$. A local minimum is defined similarly. The following is easy to see.

Proposition 4.1.3. *If $\lambda \in S$ is a local maximum then $\bar{\lambda}$ belongs to Λ_{\emptyset} . If λ is a local minimum then $\bar{\lambda}$ belongs to Λ_{\cdot} . In the remaining case, $\bar{\lambda}$ belongs to Λ_{\emptyset} .*

4.2 Relations with one-parameter subgroups. If $\lambda \in Y(T)$ then $\text{im } \lambda$ is a subtorus of T . We will denote this subtorus also by λ . From Theorem 3.4.1 it is clear that the Cohen-Macaulayness of R_{χ}^T is related to the one-parameter subgroups of T . In fact one can prove the following result.

Theorem 4.2.1. *Assume that $R_{\chi \circ \lambda}^{\lambda}$ is Cohen-Macaulay for all $Y(T) \setminus \{0\}$. Then R_{χ}^T is Cohen-Macaulay.*

Proof. First assume that X has a stable point (this is the easiest case). From the fact that $R_{\chi \circ \lambda}^{\lambda}$ is Cohen-Macaulay for all $\lambda \in Y(T) \setminus \{0\}$ we deduce from (18) that if $d_{\lambda} < d - 1$ then $H_{X_{\lambda}}^{d_{\lambda}}(X, \mathcal{O}_X)_{\chi}^T = 0$. Hence the only terms that can contribute to the right-hand side of (10) are those where $\lambda = 0$ and those where $\lambda \neq 0$, $d_{\lambda} \geq d - 1$.

Assume for some $i : \tilde{H}^{i+s-d_{\lambda}-1}(\Phi_{\lambda}, k) \otimes H_{X_{\lambda}}^{d_{\lambda}}(X, \mathcal{O}_X)_{\chi}^T \neq 0$. If $\lambda = 0$ we have that $i + s - d_0 - 1 = -1$ or $i = d - s$. If $\lambda \neq 0$ then $\Phi_{\lambda} \neq \emptyset$ and hence $i + s - d_{\lambda} - 1 \geq 0$. Combining this with $d_{\lambda} \geq d - 1$ yields $i \geq d - s$. Therefore $H_{X_{\lambda}}^i(X, \mathcal{O}_X)_{\chi}^T = 0$ if $i < d - s = h$ and hence R_{χ}^T must be Cohen-Macaulay.

Now let us treat the general case. Using induction on $\dim T$ we will reduce to the stable case.

For R_{χ}^T to be nonzero, it is necessary that χ factors through the image of T in $\text{End}_k(W)$. Hence we will assume this (otherwise the theorem is vacuous).

We then replace T with its image in $\text{End}(W)$ and χ with the character through which it factors. This construction does not change R^T nor R_χ^T .

Assume that T does not act stably on X . Then there must be a $\lambda \in Y(T) - \{0\}$ such that X does not contain a stable point for λ . Since T acts now faithfully on X we may assume that (after reindexing the α 's and possibly replacing λ with $-\lambda$) that there is a $d_1 < d$ such that $\langle \lambda, \alpha_i \rangle = 0$ if $1 \leq i \leq d_1$, and $\langle \lambda, \alpha_i \rangle > 0$ if $d_1 < i \leq d$. Let $W_1 \subset W$ be the subspace spanned by $(w_i)_{1 \leq i \leq d_1}$ and define $T_1 = T/\text{im } \lambda$. Then the action of T on W_1 factors through T_1 .

For use below we define $R_1 = k[W_1]$, $X_1 = \text{Spec } R_1$. To solve

$$(19) \quad \sum_i a_i \alpha_i = \chi$$

with $a_i \geq 0$ is equivalent to solving

$$(20) \quad \sum_{i=d_1+1}^d a_i \langle \lambda, \alpha_i \rangle = \langle \lambda, \chi \rangle,$$

$$(21) \quad \sum_{i=1}^{d_1} a_i \alpha_i = \chi - \sum_{i=d_1+1}^d a_i \alpha_i,$$

with $a_i \geq 0$.

Hence let $(\chi_j)_{j=1, \dots, N}$ be the characters of the form $\chi - \sum_{i=d_1+1}^d a_i^{(j)} \alpha_i$ where $(a_i^{(j)} = a_i)_{i=d_1+1, \dots, d}$ is a solution of (20). It is clear that there are only a finite number of such solutions. Then $(\alpha_i)_{i=1, \dots, d_1}$, $(\chi_j)_{j=1, \dots, N}$ factor through characters of T_1 . We will use the same notations for these characters. A solution to (19) does now correspond to a solution of one of the equations $\sum_{i=1}^{d_1} a_i \alpha_i = \chi_j$. Hence $R_\chi^T \cong \bigoplus_{j=1}^N R_{1\chi_j}^{T_1}$ and similarly $R^T \cong R_1^{T_1}$. It is easy to verify that these isomorphisms are compatible with each other.

By induction, it is now sufficient to show that for all $\lambda_1 \in Y(T_1) - \{0\}$ and for all j , $R_{1\chi_j \circ \lambda_1}^{\lambda_1}$ is Cohen-Macaulay. Suppose that $R_{1\chi_j \circ \lambda_1}^{\lambda_1}$ is not Cohen-Macaulay for some $\lambda_1 \in Y(T_1) - \{0\}$. By the results in §4.1 we may assume that X_1 has a λ_1 -stable point and $d_{\lambda_1} < d_1 - 1$ (possibly after replacing λ_1 with $-\lambda_1$). Let $\lambda'_1 \in Y(T)$ be a lifting of λ_1 and let $\lambda'_1 = \lambda''_1 - B\lambda$, where $B \in \mathbb{Z}$. Then λ'_1 is also a lifting of λ_1 . Furthermore if B is large enough then $\langle \lambda'_1, \alpha_i \rangle < 0$ for $i = d_1 + 1, \dots, d$. This implies that $T_{\lambda_1}^c = T_{\lambda'_1}^C$ and $d_{\lambda_1} = d_{\lambda'_1}$.

Since $R_{1\chi_j \circ \lambda_1}^{\lambda_1}$ is not Cohen-Macaulay we know from Corollary 3.4.2 that there must be a solution

$$(22) \quad b_1 \langle \lambda_1, \alpha_1 \rangle + \dots + b_{d_1} \langle \lambda_1, \alpha_{d_1} \rangle = \langle \lambda_1, \chi_j \rangle,$$

where $\text{supp}_-(b_1, \dots, b_{d_1}) = T_{\lambda_1}^c$.

(22) is equivalent to

$$b_1 \langle \lambda'_1, \alpha_1 \rangle + \dots + b_{d_1} \langle \lambda'_1, \alpha_{d_1} \rangle + a_{d_1+1}^{(j)} \langle \lambda'_1, \alpha_{d_1+1} \rangle + \dots + a_d^{(j)} \langle \lambda'_1, \alpha_d \rangle = \langle \lambda'_1, \chi \rangle$$

and $\text{supp}_-(b_1, \dots, b_{d_1}, a_{d_1+1}^{(j)}, \dots, a_d^{(j)}) = T_{\lambda'_1}^c$.

This, together with the fact that $d_{\lambda'_1} = d_{\lambda_1} < d_1 - 1 \leq d - 1$, implies that $R_{\chi \circ \lambda'_1}^{\lambda'_1}$ is not Cohen-Macaulay, which contradicts the hypothesis. \square

Theorem 4.2.1 has no converse. In fact, in §4.5, we will give counterexamples to such a converse.

4.3 Stanley's criterion. In [7] Stanley presents a tractable condition on χ for R_χ^T to be Cohen-Macaulay. We now show how this criterion follows trivially from Corollary 3.4.2 and Proposition 3.4.5.

Theorem 4.3.1 [7]. *Assume that $\chi = \sum_{i=1}^d u_i \alpha_i$ with $u_i \in]-1, 0]$. Then R_χ^T is Cohen-Macaulay.*

Proof. Assume that R_χ^T is not Cohen-Macaulay and $R_\chi^T \neq 0$ (otherwise the theorem is vacuous). Then according to Corollary 3.4.2 and Proposition 3.4.5 there exist $\lambda \in \Lambda \setminus \{\bar{\lambda}_n\}$ and $a = (a_1, \dots, a_d) \in \mathbb{Z}^d$ such that

- $\chi = a_1 \alpha_1 + \dots + a_d \alpha_d$,
- $\text{supp}_- a = \{i \mid \langle \lambda, \alpha_i \rangle \geq 0\}$.

We claim that we may assume that there is some α_i such that $\langle \lambda, \alpha_i \rangle > 0$. Suppose that this is not the case. Then, since $\lambda \approx \bar{\lambda}_n$, the hyperplane defined by λ intersects $\text{pos}\{(\alpha_i)_{i=1, \dots, d}\}$ in an α_i which is not an apex. Hence by displacing λ slightly we may make $\langle \lambda, \alpha_i \rangle$ positive without changing T_λ . In this way we have not changed the equivalence class of λ .

Since by hypothesis $\chi = \sum_{i=1}^d u_i \alpha_i$, $u_i \in]-1, 0]$ we obtain that

$$\sum_{i=1}^d (a_i - u_i) \langle \lambda, \alpha_i \rangle = 0.$$

For a particular i there are two possibilities:

- $\langle \lambda, \alpha_i \rangle \geq 0$. Then $a_i < 0$ and hence $a_i - u_i < 0$.
- $\langle \lambda, \alpha_i \rangle < 0$. Then $a_i \geq 0$ and hence $a_i - u_i \geq 0$.

It follows that for every i either

$$(23) \quad a_i = u_i = 0 \quad (\text{and hence } \langle \lambda, \alpha_i \rangle < 0)$$

or

$$(24) \quad \langle \lambda, \alpha_i \rangle = 0.$$

Hence $\forall i : \langle \lambda, \alpha_i \rangle \leq 0$ which contradicts our hypothesis about λ . \square

4.4 Finiteness. In this section we will look for a condition under which there are only a finite number of χ such that R_χ^T is Cohen-Macaulay. To simplify things we will assume that X has a stable point.

We start with two elementary lemmas, whose proof will be left to the reader.

Lemma 4.4.1. *Let E be a vector space, and assume that $x_1, \dots, x_m \in E$. Let B be the cone spanned by the $(x_i)_i$. Then there exists an x such that*

$$(x + B) \cap \left(\sum_{i=1}^m \mathbb{Z} x_i \right) \subset \sum_{i=1}^m \mathbb{N} x_i.$$

Lemma 4.4.2. *Let E be a vector space. Assume that $(B_i)_{i=1, \dots, m}$ is a set of polyhedral cones in E such that $E - \{0\} = \bigcup_{i=1}^m \text{int } B_i$. Let $(u_i)_{i=1, \dots, m} \in E$. Then $\bigcup_{i=1}^m (B_i + u_i)$ has bounded complement.*

We will now verify the hypothesis for Lemma 4.4.2 in the special case we are interested in. Denote by Λ_{\max} the set of maximal elements for the partial ordering defined on $\Lambda - \{0\}$ by (14).

Lemma 4.4.3. *Assume that X has a stable point. Then*

$$\bigcup_{\bar{\lambda} \in \Lambda_{\max}} \text{int } B_{\bar{\lambda}} = E - \{0\}.$$

Proof. Let $\chi \in E - \{0\}$. Write

$$\chi = \sum_{i \in T} a_i \alpha_i \quad \text{all } a_i > 0$$

with T minimal. It is then well known that the $(\alpha_i)_{i \in T}$ are independent (compare with [1, Example 2.3.6]). To see this assume that there is a nontrivial dependency $0 = \sum_{i \in T} b_i \alpha_i$. Then for some t , $\chi = \sum_{i \in T} (a_i - tb_i) \alpha_i$ will have positive coefficients, but smaller support than T . This contradicts the choice of T . Hence there are $\mu \in E^*$ such that $\langle \mu, \alpha_i \rangle < 0$ for all $i \in T$.

We then deduce from Lemma 3.6.5 that there are $\bar{\lambda} \in \Lambda_{\max}$ such that

$$\chi \in \text{relint pos}\{(\alpha_i)_{i \in T}\} \subset \text{relint } A_{\bar{\lambda}} \subset \text{int } B_{\bar{\lambda}},$$

where the last inclusion follows from Lemma 3.5.2 and Lemma 3.6.6. \square

The following result will be the main theorem of this section.

Theorem 4.4.4. *Assume that X has a stable point. Then the following are equivalent.*

- 1 . $\forall \lambda \in \Lambda_{\max} : |T_{\lambda}| > u_{\lambda}$.
- 2 . *There are only a finite number of $\chi \in X(T)$ such that R_{χ}^T is nonzero and Cohen-Macaulay.*

Proof. (1) \Rightarrow (2) Assume that (1) holds. Denote by M the subsemigroup of $X(T)$ generated by $\alpha_1, \dots, \alpha_d$. Since X is assumed to have a stable point, it is easy to see that M is a group. Furthermore it is clear that $R_{\chi}^T \neq 0 \Leftrightarrow \chi \in M$.

Let λ be an arbitrary element of Λ_{\max} . Then by Theorem 3.6.3

$$\tilde{H}^i(\Phi_{\lambda}, k) = \tilde{H}^{i-1}(\Phi'_{\lambda}, k) = \begin{cases} k & \text{if } i = u_{\lambda} - 1, \\ 0 & \text{otherwise.} \end{cases}$$

One deduces that if

$$(25) \quad i = h - (|T_{\lambda}| - u_{\lambda}), \quad \text{then } \tilde{H}^{i+s-d_{\lambda}-1}(\Phi_{\lambda}, k) \neq 0.$$

Note that $h - (|T_{\lambda}| - u_{\lambda}) < h$ by hypothesis. Let $\chi \in M$ and assume that R_{χ}^T is Cohen-Macaulay. Then by (25) and Corollary 3.4.2 χ will not be of the form

$$\sum_{i=1}^d a_i \alpha_i \quad \text{where } \begin{cases} a_i \geq 0 & \text{if } i \in T_{\lambda}, \\ a_i < 0 & \text{if } i \notin T_{\lambda}, \end{cases}$$

or equivalently χ will not be in the set

$$\sum_{i \in T_{\lambda}^c} (-\alpha_i) + \sum_{i \in T_{\lambda}} \mathbb{N} \alpha_i + \sum_{i \in T_{\lambda}^c} \mathbb{N}(-\alpha_i).$$

Now by Lemma 4.4.1 there will be a $c_{\lambda} \in B_{\lambda}$ such that

$$\sum_{i \in T_{\lambda}} \mathbb{N} \alpha_i + \sum_{i \in T_{\lambda}^c} \mathbb{N}(-\alpha_i) \supset (B_{\lambda} + c_{\lambda}) \cap M.$$

Hence χ will not be an element of

$$(26) \quad \bigcup_{\lambda \in \Lambda_{\max}} \left(B_{\lambda} + c_{\lambda} + \sum_{i \in T_{\lambda}^c} (-\alpha_i) \right).$$

Now from Lemma 4.4.1 and Lemma 4.4.2 it follows that (26) will have bounded complement. Hence there are only a finite number of possibilities for χ .

(2) \Rightarrow (1). Assume that there is a $\lambda \in \Lambda_{\max}$ such that $|T_{\lambda}| = u_{\lambda}$.

From the Hochster-Roberts theorem we know that R^T is Cohen-Macaulay. Let

$$\chi = \sum_{i \in T_{\lambda}} b_i \alpha_i \quad \text{all } b_i \in \mathbb{N}.$$

Then to solve

$$(27) \quad \chi = \sum_{i=1}^d a_i \alpha_i \quad \text{all } a_i \in \mathbb{N}$$

we have to solve

$$(28) \quad \sum_{i \notin T_{\lambda}} a_i (-\alpha_i) = \sum_{i \in T_{\lambda}} (a_i - b_i) \alpha_i.$$

Now the left-hand side of (28) is in $B_{\lambda} \cap E_{\lambda} = A_{\lambda}$ (using Lemma 3.6.6) and hence all $(a_i - b_i)_{i \in T_{\lambda}}$ must be positive (here we use the hypothesis that $|T_{\lambda}| = u_{\lambda}$). This means that there must be a one-one correspondence between the solutions to (27) and the solutions to

$$0 = \sum_{i=1}^d a'_i \alpha_i \quad \text{all } a'_i \in \mathbb{N}$$

by putting $a_i = a'_i + b_i$.

Therefore $R_{\chi}^T \cong R^T$ as R^T -modules and hence R_{χ}^T is Cohen-Macaulay. Since there are an infinite number of choices for χ , we are done. \square

4.5 An explicit example. In this section we will determine, for a particular pair (T, W) , exactly when R_{χ}^T is Cohen-Macaulay. In particular we obtain counterexamples to the converses of Theorems 4.2.1 and 4.3.1. It should be noted that Stanley has already given a simple counterexample to the converse of Theorem 4.3.1 [8, Example 3.7]. If we analyze this example with the help of Corollary 3.4.2 then we see that it is based on the fact that for some λ 's, d_{λ} may be so large that the term in (10) involving $H_{\chi_{\lambda}}^{d_{\lambda}}(X, \mathcal{O}_X)$ does not contribute to $H_{\chi_{\lambda}}^i(X, \mathcal{O}_X)$ for $0 \leq i < h$. This situation is somewhat special however, and it will not happen if d is large enough and the weights of W are distributed randomly in $X(T)$. In contrast our examples will not be based on the fact that the d_{λ} may be large.

We will take $\dim T = 2$. In that case $E \cong E^* \cong \mathbb{R}^2$ and the pairing $\langle \cdot, \cdot \rangle$ will be given by the usual inner product $\langle (x_1, x_2), (y_1, y_2) \rangle = x_1 y_1 + x_2 y_2$. In the sequel we will denote the elements of E and E^* by the corresponding elements in \mathbb{R}^2 .

We will choose $W = (-1, 0)^{\oplus 2} \oplus (0, 1)^{\oplus 2} \oplus (1, 1)^{\oplus 2} \oplus (1, -1)^{\oplus 2}$. Here the exponent 2 was chosen to avoid the low-dimensional anomalies described above. Bigger exponents work equally well.

TABLE 2

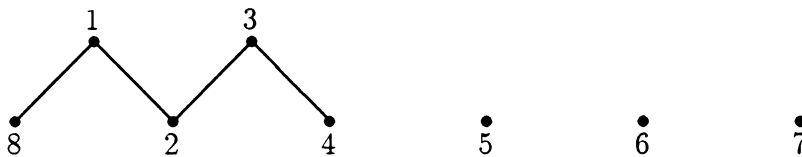
| | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
|-------------|--------|--------|---------|---------|----------|----------|---------|---------|
| λ | (2, 1) | (1, 2) | (-1, 2) | (-2, 1) | (-2, -1) | (-1, -2) | (1, -2) | (2, -1) |
| d_λ | 6 | 6 | 6 | 4 | 2 | 4 | 2 | 4 |
| u_λ | 1 | 2 | 1 | 2 | 2 | 2 | 2 | 2 |

Now $\Lambda - \{\bar{0}\}$ consists of eight elements, given by Table 2.

In this table, $\lambda_1 - \lambda_8$ are listed in counter clockwise direction and hence we deduce from Proposition 4.1.3 that $\Lambda_\emptyset = \{\bar{\lambda}_1, \bar{\lambda}_3, \bar{\lambda}_6\}$ and $\Lambda_{..} = \{\bar{\lambda}_2, \bar{\lambda}_5, \bar{\lambda}_7\}$. If we then apply Remark 4.1.2 we obtain Figure 1.

A few words of explanation are due here. The weights of W have been represented by fat dots. Hence there are four fat dots, each representing a weight with multiplicity two. The origin has been marked by a + -sign.

The shaded area represents the elements χ of $X(T)$ where R_χ^T is not Cohen-Macaulay. Hence there are only a finite number of χ such that R_χ^T is Cohen-Macaulay. Since for every $\lambda \in \Lambda - \{\bar{0}\}$, $|T_\lambda| > u_\lambda$, this is consistent with Theorem 4.4.4. Note that the PO -set structure defined by (15) on Λ is



The interior of the region bounded by the dashed lines in Figure 1 are the characters of the form $\sum_{i=1}^d u_i \alpha_i$, $u_i \in]-1, 0]$. In this case (but not always) these are precisely the characters which satisfy the hypothesis of

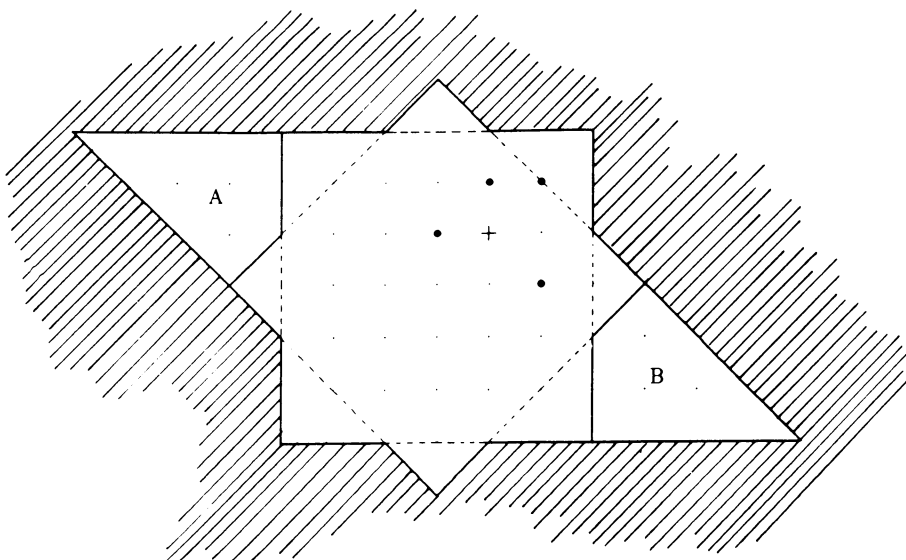


FIGURE 1

Theorem 4.2.1. Since they do not fill all of the white area we obtain counter-examples to Theorems 4.2.1 and 4.3.1.

Furthermore the regions marked by A and B are those points where $H_{X_{\lambda_4}}^{d_{\lambda_4}}(X, \mathcal{O}_X)_X^T$ and $H_{X_{\lambda_8}}^{d_{\lambda_8}}(X, \mathcal{O}_X)_X^T$ are nonzero. But since λ_4 and λ_8 are contained in Λ , λ_4 and λ_8 have no influence on the Cohen-Macaulayness of R_X^T .

4.6 The functional equation. Since R_X^T is a \mathbb{Z}^d -graded object, it has a Poincaré series $P(R_X^T, t)$ where $t = (t_1, \dots, t_d)$. It is well known that this Poincaré series is a rational function. Let $\psi = -\chi - \alpha_1 - \dots - \alpha_d$. In [7] and [8] Stanley shows that often the following functional equation holds

$$(29) \quad P(R_X^T, t) = (-1)^h t_1^{-1} \dots t_d^{-1} P(R_\psi^T, t^{-1}).$$

In [7] he also gives necessary and sufficient conditions for (29) to hold.

We will do the same thing (if X has a stable point) using Corollary 3.4.2. As a result, we obtain that if $\dim T \leq 3$ and X has a stable point then the fact that (29) holds, implies that R_X^T is Cohen-Macaulay.

If $P(R_X^T, t)$, $t = (t_1, \dots, t_d)$ is a rational function then we will (as in [7]) denote by $P(R_X^T, t)_\infty$ the Laurent series expansion of $P(R_X^T, t)$ around ∞ . This is then a Laurent series in $t_1^{-1}, \dots, t_d^{-1}$. Furthermore the local cohomology modules $H_{(R^T)_+}^i(R_X^T)$ are Artinian and hence it is possible to define their Poincaré series as an element of $t^\gamma \mathbb{Z}[[t_1^{-1}, \dots, t_d^{-1}]]$ for some $\gamma \in \mathbb{Z}^d$. There is the following identity [7],

$$(30) \quad P(R_X^T, t)_\infty = \sum_{i=0}^h (-1)^i P(H_{(R^T)_+}^i(R_X^T), t).$$

Note however that $H_{(R^T)_+}^i(R_X^T) = 0$ if $i < 0$ or if $i > h$. Hence the bounds in the summation on the right-hand side of (30) are immaterial.

Using (10) we may then compute

$$\begin{aligned} P(R_X^T, t)_\infty &= \sum_{\lambda \in \Lambda} \sum_{i=-\infty}^{\infty} (-1)^i \dim \tilde{H}^{i+s-d_\lambda+1}(\Phi_\lambda, k) P(H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X)_X^T, t) \\ &= \sum_{\lambda \in \Lambda} (-1)^{d_\lambda-s+1} \tilde{\chi}(\Phi_\lambda) P(H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X)_X^T, t). \end{aligned}$$

Let us from now on assume that X has a stable point. In that case $\Phi_0 = \emptyset$.

We then obtain

$$\begin{aligned} P(R_X^T, t)_\infty &= (-1)^{d-s} P(H_0^d(X, \mathcal{O}_X)_X^T, t) \\ &\quad + \sum_{\lambda \in \Lambda \setminus \{0\}} (-1)^{d_\lambda-s+1} \tilde{\chi}(\Phi_\lambda) P(H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X)_X^T, t). \end{aligned}$$

Since X has a stable point, $d-s = h$. Furthermore using Corollary 3.3.2 we see that $P(H_0^d(X, \mathcal{O}_X)_X^T, t) = t_1^{-1} \dots t_d^{-1} P(R_\psi^T, t^{-1})$.

Hence we obtain

$$\begin{aligned} P(R_X^T, t) &= (-1)^h t_1^{-1} \dots t_d^{-1} P(R_\psi^T, t^{-1}) \\ &\quad + \sum_{\lambda \in \Lambda \setminus \{0\}} (-1)^{d_\lambda-s+1} \tilde{\chi}(\Phi_\lambda) P(H_{X_\lambda}^{d_\lambda}(X, \mathcal{O}_X)_X^T, t). \end{aligned}$$

It also follows from Corollary 3.3.2 the $H_{\chi_\lambda}^{d_\lambda}(X, \mathcal{O}_X)_\chi^T$ all have distinct negative support.

We have now proved the following theorem.

Theorem 4.6.1. *Assume that X has a stable point. Then (29) holds if and only if for all $\lambda \in \Lambda \setminus \{0\}$ either $\tilde{\chi}(\Phi_\lambda) = 0$ or there does not exist $a = (a_1, \dots, a_d) \in \mathbb{Z}^d$ with $\text{supp}_- a = S_\lambda^c$ such that $\chi = a_1 \alpha_1 + \dots + a_d \alpha_d$.*

We may use this theorem to prove the following result.

Proposition 4.6.2. *Assume that X has a stable point and $\dim T \leq 3$. Then if (29) holds then R_χ^T is Cohen-Macaulay.*

Proof. In this situation if $\lambda \neq 0$ then $\tilde{\chi}(\Phi_\lambda) = -\tilde{\chi}(\Phi'_\lambda)$ (Φ'_λ was introduced in Proposition 3.4.4). Φ'_λ is a subcomplex of the boundary complex of a spherical polytope of dimension $s - 1$. It follows by inspection that if $\tilde{\chi}(\Phi_\lambda) = 0$ then $\tilde{H}^*(\Phi_\lambda, k) = 0$. Hence combining Corollary 3.4.2 and Theorem 4.6.1 yields that R_χ^T must be Cohen-Macaulay. \square

Remark 4.6.3. If $\dim T \geq 4$ then Proposition 4.6.2 is no longer true. For example if $\dim T = 4$ then Φ'_λ may be the disjoint union of a circle and a point. Then $\tilde{\chi}(\Phi_\lambda) = -\tilde{\chi}(\Phi'_\lambda) = 0$ but not all $\tilde{H}^i(\Phi_\lambda, k)$ are zero.

It is possible to construct an explicit counterexample, but we will not bother to do so.

A result similar to Theorem 4.4.4 can also be proved.

Theorem 4.6.4. *Assume that X has a stable point. Then there are only a finite number of χ such that (29) holds.*

Proof. Given Theorem 4.6.1, the proof of the present theorem is completely similar to the proof of $1 \Rightarrow 2$ in Theorem 4.4.4 except that (25) is replaced by $\tilde{\chi}(\Phi_\lambda) \neq 0$. \square

Note added in proof. A result, similar to Theorem 4.4.4, but valid for general reductive groups, meanwhile has been obtained by M. Brion (*Sur les modules de covariants*, preprint Institut Fourier 91). His proof is very different from ours.

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